

KDU/PRO/CAP/ 102 /2022		General Sir John Kotelawala Defence University,
		KandawalaEstate, Ratmalana, Sri Lanka.
<u> </u>		T: Phone: 2632028, 2622995
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A		22 / 03 / 2022
INVITATION TO BID AND GI	ENERAL CONDITIONS OF TENDER	

1. The Vice Chancellor of the General Sir John Kotelawala Defence University, as the Chairman, Department Procurement Committee Invites Bid/s from prospective Bidders for supply of <u>item/s listed in the schedule in Annex "A"</u>. The relevant specifications of the item/s are indicated in Annex "B".

2. <u>CLOSING DATE & TIME</u>. The tender will close at 1000 hrs. on 21 /04 /2022. Any Bid submitted afterthe closing time of the tender will be rejected & unopened such bids will be returned to the bidder.

3. <u>VALIDITY OF BID.</u> The bid submitted under this tender <u>must be valid for a period of 120 days from the date of closing of tender.</u>

4. BID BOND / GUARANTEE.

- (b) Submission of insufficient Bid Bond/Guarantee value or period will be considered as a "major deviation" and such offer will not be considered for further procurement action and will be rejected.
- 5. <u>VALUE ADDED TAX</u>. The Bidders who bid for locally delivered items must have the VAT registration. The VAT portion must be shown separately in the price schedule in Annex "A" and VAT registration number must be indicated. If the quoted item is exempted from VAT or Bidding Company is not liable for VAT, reference number and date of relevant Act number/Gazette notification/a certificate (as applicable) <u>issued for the current financial year</u> from the Commissioner General of Inland Revenue to that effect should be submitted along with the Bid.
- 6. BID SUBMISSION. The bidder must duly sign at the last page (before Annexes) of this document indicating the name of the signatory and the name of the company & place the company common seal to confirm the acceptance of tender conditions. The Bid/s that do not include authorized signature will be rejected. The Bid/s duly signed by the bidder enclosed and sealed in an appropriate cover addressed to the following address should be sent by registered post or could be deposited in the appropriate tender box placed at General Sir John Kotelawala Defence University. Kandawala Estate. Ratmalana (at the Main Entrance of General Sir John Kotelawala Defence University) on or before the time & date specified for the closing of tender. The tender reference number, date & time of closing tender should be indicated & underlined at the top left corner of the envelop.

 The Chairman,
Department Procurement Committee,
General Sir John Kotelawala Defence University,
Kandawala Estate, Ratmalana,
Sri Lanka.

7. The Bid/s must be submitted in the attached schedule of prices in Annex "A" as applicable. However, bidders could use similar formats prepared with their own letter heads with all the details mentioned therein and submit in three copies along with duly signed copy of a General Conditions of tender. The Bid/s must contain Technical Literature, Pamphlets, Drawings and Quality Standard Certificate etc necessary to determine characteristics of items offered and in case of Machinery/Vehicles & Equipment, servicing and workshop data/after sales service, back up facilities or any other facilities provided by the supplier.

8. <u>SUBMISSION OF SAMPLES/PAYMENT OF TESTING CHARGES</u>.

When it is required to submit samples, <u>every offer</u> must be accompanied with pre - marked samples. The marking of samples <u>indicating the Bidder & Offer number</u> must be done and the samples must be handed over to the officer at same place where tender box is placed <u>on or before the closing date & time of the Bid</u>. Samples submitted after closing time of the Bid will be rejected. The documents such as Air Way Bills etc, will not be accepted in place of samples. When the testing charges are required to be paid, bidders shall pay testing charges separately <u>for all offers</u> indicated in their bid/s.

(1) Samples. Please submit samples.

(2) <u>Testing Charges</u>. A sum of Rs......<u>per offer</u> must be paid to the Bursar of KDU, prior to the submission of bid and a copy of the receipt must be annexed to the bid. It is the responsibility of bidder to inform the Cashier of the Account Office to note the tender number on the receipt issued for such payments.

8. <u>BID OPENING</u>. All duly received bids <u>will be opened immediately after the scheduled closing time of Bids at the same venue</u>. Bidders or their accredited agents could be present at the time of opening of bids.

9. PRICES.

For locally delivered items (including locally manufactured items & foreign items imported by the bidders) price must be quoted in Sri Lankan Rupees, inclusive of all charges for delivery of items to General Sir John Kotelawala Defence University Ratmalana, Faculty of Allied Health Science (FAHS) Werahera and University Hospital Werahera or Southern Campus Sooriyawewa. Unit price, VAT and Total price should be clearly indicated in schedule in Annex "A". Other than VAT, all other type of taxes (eg: NBT, BTT, etc.) should not be indicated separately and should be included in unit price.

- Invitation to Bids are circulated a m o n g, the registered suppliers with RESTRICTED TENDERS. Ministry of Defence (MOD), only bids submitted by registered suppliers will be allowed for consideration. However, Chairman, Department Procurement Committee reserves the right to invite the bids from multiple combinations of Procurement Methods as stipulated in Chapter III of the Government Procurement Guideline, 2006 to ensure highest competitiveness.
- PERFORMANCE BOND/GUARANTEE A successful bidder shall f u r n i s h a Performance Bond/Guarantee in the form of "On Demand" & "Unconditional" Bank/Insurance Guarantee for a sum equivalent to 10% of the contract value for every contract that exceeds Rs. 2,000,000.00 or equivalent amount in foreign currency through a recognized Commercial Bank registered in Sri Lanka or through an Insurance Company authorized by the Insurance Board of Sri Lanka to issue such Performance Guarantee for this purpose, within two weeks from the date of notification of award. The proceeds of the Performance Bond/Guarantee shall be payable to the Vice Chancellor of the General Sir John Kotelawala Defence University as compensation for any loss resulting from the supplier's failure to complete his performance obligations under the contract. If the contracted supplier fails to deliver the items on time or fails to complete the works as per the agreed contract, THE TOTAL VALUE OF THE PERFORMANCE BOND/GUARANTEE will be forfeited. If only partial delivery is made during the agreed contract period, the corresponding value percentage of undelivered quantity from the Performance Bond/Guarantee will be forfeited.
- SIGNING OF CONTRACT. The notification of award will be transmitted to the successful bidder by post, by fax or e-mail. This notification constitutes the formation of the contract. The successful bidder should submit his written acceptance for the award and performance bond / guarantee (For awards over Rs. 500,000.00 without VAT) within 14 days of receipt of such notification. Upon acceptance of the award and furnishing of the Performance Bond/Guarantee, the successful bidder will have to enter into a formal contract with the Vice Chancellor of the General Sir John Kotelawala Defence University by signing the Contract.
- Preference will be given for early delivery. In case of bulk supplies for locally manufactured items, the delivery of total quantity must be completed within 120 days of signing of contract, unless mutually agreed for extended delivery period with General Sir John Kotelawala Defence University. The bidder/s must indicate the proposed delivery schedule in Annex "D". In the event of placing a purchase order with the successful bidder, the total quantity so ordered must be supplied as one consignment unless part deliveries are agreed upon in the contract. The deliveries not made as per agreed delivery schedule will be considered as bad performances by the suppliers and no extended delivery period will be authorized. Under extreme unavoidable conditions too, the Chairman, Department Procurement Committee (Vice Chancellor of the General Sir John Kotelawala Defence University) reserves the right to grant or refuse delivery period extensions only within the current financial year with or without liquidated claim for delayed deliveries and that decision will be final.
- LIOUIDATED DAMAGES. In case of delivery period extensions requested by the successful bidder, a sum equivalent to 1% of the total value of the delayed supply per delay of one week or part thereof may be deducted from the payment due to the supplier from the General Sir John Kotelawala Defence University as liquidated damages up to the maximum limit of 12% of the total value of delayed supplies.
- PAYMENT TERMS FOR LOCALLY DELIVERED ITEMS. Payment will be made after acceptance of items which should be subjected to a pre-acceptance inspection/testing by General Sir John Kotelawala Defence University authorities. The delivery made to the General Sir John Kotelawala Defence University should not be considered as quantities taken over by General Sir John Kotelawala Defence University until items are properly accepted after pre-acceptance inspection. Any item that does not conform to the specifications or already approved sample will be rejected & it is the responsibility of the supplier to remove them from General Sir John Kotelawala Defence University stores/premises within 07 working days of such intimation (either verbal or written) at his own cost and replace them with items conforming to specification within one month of such rejection. The bidder shall allow approximately 60-90 days' period of credit from the date of acceptance of items for Account Office, General Sir John Kotelawala Defence University to obtain liquid cash from General Treasury & release the payment.
- RIGHTS OF THE PROCUREMENT COMMITTEE. The Department Procurement Committee reserve the right to accept or reject whole or part of this tender and their decision will be final. The successful bidders will be notified. Information with regard to rejected or unsuccessful bids will not be communicated.

Thanking You, Yours faithfully,

SA Kumaranayaka For Vice Chancellor

General Sir John Kotelawala Defence University I/We agree to abide by the conditions of tender and undertake to supply the items as per delivery schedule mentioned in the contract, in the event of an order been placed with me/my firm/company as a result of this tender. Signature

Date :	Company seal
Name of the Company/Bidder	



SCHEDULE OF PRICES FOR LOCALLY DELIVERED ITEMS

S/N	ITEMS		DENO	QTY	PRICE EACH SLRS	TOTAL PRICE SLRS
15.5	PURCHASE OF CIM/FMS TRAINI	NG				
	SYSTEM FOR MECHANICAL ENGINEERING DEPARTMENT					
01	CIM/FMS Training System		No's	01		
	As per attached specification					
30, 40 (TOTAL					
	DISCOUNT					
	TOTAL(AFTER DISCOUNT)					
	VAT %					
	GRAND TOTAL OTHER DETAILS					
	(i) DELIVERY PERIOD (ii) MAKE & MODEL (iii) VALIDITY PERIOD (iv) WARRANTY PERIOD (v) PAYMENT TERMS (vi) COUNTRY OF ORIGIN (vii) DISCOUNT IF ANY (viii) ANY OTHER TAXES VAT DETAILS PLACE OF DELIVERY	DEPAI - SIR J KAND	VALUE IFICATE RTMENT ITEMS JOHN F	ADED / VAT OF INL TO BE KOTELA	TAX PERMA EXEMPTION AND REVEN DELIVEREN	NENT REGISTRATION N LETTER ISSUED BY IUE TO BE ATTACHED D TO THE "GENERAL FENCE UNIVERSITY, NA ALONG WITH THE
	Any queries / information with a from Officer Commanding Log Defence University through e-maduring working hours.	istics Se	ervices	office a	t General	Sir John Kotelawala
	NOTE: UNIT PRICE AND TOT THE TENDER, IF NOT QUOTA SUPPLIER NAME					ATED CLEARLY IN
	ADDRESS					
	CONTACT NUMBER					Company Seal
	E MAIL ADRESS					
(E)	Bid Reference: KDU/PRO/CAP/	102 /202	2		,	



THE CIM/ FMS TRAINING SYSTEM

Overview

Flexible manufacturing system has processing equipment like a robot, CNC lathe, CNC machining center, and a series of hardware and software like robot slide guide rail, conveyor belt, smart cameras, servers, control software, and service software. The system uses advanced control strategies and service software, which integrate hardware to achieve the intelligent communication and collaboration of people, machined parts, and machines. Truly achieve the industrial 4.0 which featured as the Internet of things, mobile Internet, big data, cloud computing, and other emerging technologies, etc.

The expected outcomes

- Understand, operate, troubleshoot, and optimize production lines.
- Have an advanced understanding of electrical, mechanical, hydraulic, and pneumatic systems
- Troubleshoot and tune complex electrical and mechanical components of production lines
- Operate and modify PLC programs, operate and program HMI (Human Machine Interface).
- Operate manufacturing machines including an in-depth understanding of CNC programming, CAD, and CAM software
- Be fully familiar with machine vision systems and product identification techniques.
- Integrate smart sensors and inputs into automation-controlled systems
- Gain a solid understanding of the advanced concepts and components of Industry 4.0 manufacturing.

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Candidate CIM/FMS Training system

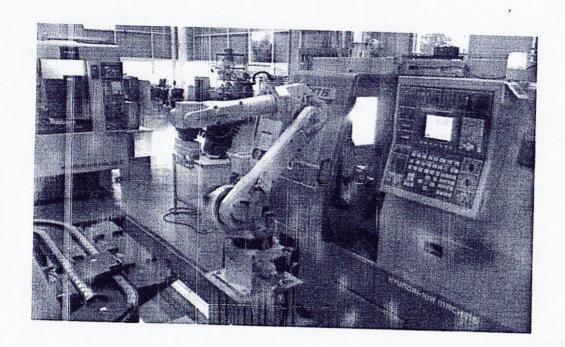


Fig. 1 The CIM/ FMS system with CNC turning center, Robot arm, and conveyer system

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Ms. HDI Piyumini Lecturer (Probationary)

TECHNICAL SPECIFICATIONS OF CIM/FMS TRAINING SYSTEM

Equipment	Specifications	Estimated cost
CIM/FMS system	The Flexible Manufacturing System (FMS) needs to expose students to automation	22M
	and industrial applications by combining CNC technology with robotics and	
	materials handling. Students should be able to develop and edit programs, record	
	precise robotic positions, accurately mill/turn parts, and synchronize mill/turn and	
	robot operation. Students should gain "virtual hands-on" experience in CNC and	
	robot programming, especially in I/O commands.	
	These packages can be able to use as a stand-alone work cell, or integrated within a	
	CIM system. The robot tends the CNC machine and performs other part manipulation	
W	and/or assembly tasks. When used in a CIM system, the robot loads and unloads parts	
	to and from the CIM conveyor. The robot is mounted on a base for mobility and a	
	larger work area.	
No Station	Technical Specifications	
1. CNC Turning	a) Turning Center can be linked with robot FMS/CIM	
Center	b) Swing over bed: 210mm	
X	c) Chuck diameter: 100mm	
	d) Spindle speed:100-1750r/min (control speed by G code)	

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	(0	Chinal Almanat. 1.1. 25
	5	c) Spinare unough-noie: 25mm
	(J	f) Spindle mount: MT4
	8	g) Spindle motor power: 1100W
	(h	h) X travel: 80mm
	i)	Z travel:290mm
	j)	The max moving speed: 4000mm/min
	k)	X/Z motor:400W Servo Motor
	1)	The max feeding speed: 2000mm/min
	(m	m) MPG hand wheel:4 axis
	(u	n) Tool position: 4
	(0	Tool dimension: 10*10mm
	(d	Tailstock taper: MT2
	a	q) Travel of tailstock: 50mm
	(L)	r) Positioning accuracy: 0.03mm
	s)	s) Repeatability accuracy: 0.02mm
	t)	t) Power: single phase 230VAC
10° 10° 10° 10° 10° 10° 10° 10° 10° 10°	(n	u) Weight(NW/GW): 330/350KG
	(A .	v) Electric Auto Door feeding speed:90mm/s
	(w)	w) Pneumatic three-jaw chuck:110mm

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	Q.	1
o. Minimum protection level: IP54		1
n. Maximum arm span : ≥ 1389mm	NE NY	
m. working temperature 0-45°C;		
l. 6 axis travel(arm rotation): 360°	The other	17
k. 5 axis travel(arm swing): ±120°	2	1.2
j. 4 axis travel(arm rotation) : ±185°		
i. 3 axis travel(upper arm): +145°/-105°		
h. 2 axis travel(lower arm)+135°/-100°		
g. 1 axis travel(bottom rotation): 170°		
f. 6 axis(arm rotation): 900°/sec.		
e. 5 axis(arm swing): 450°/sec.	2.0	
d. 4 axis(arm rotation): 360°/sec.		
c. 3 axis(upper arm): 375°/sec.		
b. 2 axis (lower arm): 270°/sec.		
a. I axis(bottom rotation):337.5°/sec.	•	
1. Technical parameter:		
action requirements.		
6 Axis Robot grabs the workpiece and places it on the machine tool to process and complete the relevant	o Axis Robot	

Pneumatic multi-functional gripper with an optical sensor Ethernet interface incl. real-time joint control j) Station trolley with profile platek) User panel with emergency stopl) Pneumatic equipment including maintenance unit c) Position detection method: absolute encoder Position repeatability: ±0,02 mm or better Max. number of additional axes: 8 Maximum load capacity: min. 2 kg Power supply 230 V, max. 2 kVA Pneumatic hand interface 32 digital Inputs/Outputs b) Drive system: AC servo motors m) The power supply unit 24 V a) 6-axes articulated robots USB interface n) Robot interface box Robot station basic equipment Robot controller Electric cabling 2. Industrial robot Teach box (p (g) (e)

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Process module robot handling

Workpiece socket with sensor

Input slide module

inch monitor, keyboard, and mouse.		•
15. Computer - A Desktop computer with an i7 processor, 8 GB RAM, 1 TB HDD, DVD ROM, 23-	.000	
14. Installation / Training session / after sales service required.		
13. A practical //workbook for students is required for operating the robot standalone activities.		
12. Expected function of the system is given in annexure B.		
grippers and manipulations.		
11. The robot arm should be teachable, programmable and custamizable for different practicals with		
from the CIM conveyor.		
and manipulation tasks. When used in a CIM system, the robot loads and unloads parts to and		
10. This station should be able to operate as a standalone station to perform customized assembly		
EN 60204-1 and DIN EN ISO 12100.		
9. The robot arm should satisfy the EU Machinery Directive 2006/42/EC in compliance with DIN		
cells		
8. Software package with a dual-user license for online programming and visualization of robot		
7. Software package with a eight-user license for offline programming and simulation of robot cells.		
caps, springs, and pistons		
6. Workpiece set consisting of 12 cylinder bodies in the colours red, black, and silver as well as end		
h) The compressor should be able to be kept inside an active classroom.		
g) Pressure regulator valve with gauge		
f) Duty cycle: max. 50 %		
e) Noise level: $\leq 45 \text{ dB (A)/1 m}$		
d) Compressed air outlet: 1/4" or KD4		

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w axes) considered) can be turn or mill either CNC (optional-**CNC Milling** Center (3 q) Repeatability accuracy: 0.02mm p) Positioning accuracy: 0.03mm m) Rapid movement in X/Y/Z Axis: 1-4000mm/min l) Motor Type: X/Y/Z axis are AC Servo o) Power of X/Y/Z Axis: AC Servo 750W n) Feed rate in X/Y/Z Axis: 1-2000mm/min k) Spindle speed: 100-24000rpm 力 و C b) Y-axis travel: minimum 175mm Table size: 450*160mm Transmission: ball screw Spindle Power: 1.5kw Number of T-slots: 3 MPG handwheel: 3 axis Control system: Run ISO G code Standard Size Collet: 1mm- 13mm Spindle taper: ISO 20 X-axis travel: minimum 300mm Z-axis travel: minimum 270mm Tool DIA. Range: 1-13mm Tool number: 10

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		v) Table structure: Full cast iron
(4)		w) Power: Single phase 230VAC
		x) Weight(NW/GW): 500/550kg
		y) Electric Auto Door feeding speed:90mm/s
4	Conveyors	According to the material circulation in the production process of the actual factory, the circular produce
		line completes the whole circulation flow of the products in the whole production line.
		A conveying process with electro-pneumatic sorting of parts being conveyed.
		Each sorting station is programmed to discern specific part characteristics (Metallic or non-metallic or
		by colour). Based upon this determination, parts are pushed
1 -		Conveyor speed and directional control is done via a Variable Frequency Drive control system. A PLC
		dedicated to the aforementioned activities is used to control
		sorting station. The proposed laboratory practical from this section is provided in Annexure A
		The practical will be operated and controlled using Programmable logic controller (PLC) and Desktop
		computer.
		1. Structure :
		a) The fixed frame is made of aluminium profiles
		b) Adopt adjustable lifting metal foot cup
	* **	c) Chain plate connection
		d) Size: L*W 2*1.5M; Perimeter 7m

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		*	70			•		9				RFID System					
k) Working temperature : −10°C~+65°C	j) Protection level: IP67	i) communication protocol: Modbus	h) Communication interface: RS485	g) Card reading distance: 1cm	f) Card reading tips : Indicator light (indicator light flashes when reading card)	e) Maximum power consumption: 1W	d) RF output power: 0.1W	c) 3.Voltage: +12V~+24V DC	b) Standard: SO/IEC 15693/ISO 18000-3M1	a) Working frequency: 13.56MHz	and submits the data to the upper computer, and the upper computer performs the corresponding action Technical parameter	The RFID system unit identifies the material by reading the electronic	c) Feeding speed: 1-7M/min	b) Motor drive mode: PLC Control drive	a) AC motor power >= 200W	2. Technical Parameter	e) Feeding and discharging blocking mechanism: air Cylinder
					reading card)						rforms the corresponding action	electronic tag of the material on the Pallet,					

Mr.RMRC Udayanandana Station : 3 acc Management conveyor with the help of sensors and actuators that are built into the stop stations. Various PLC types The PLC (Programmable Logic Controller) should control and monitor the flow of pallets on the To achieve a proper pallet tracking function the following additional products are required (Siemens, Omron, etc.,) and field bus systems (digital I/O, PROFIBUS, ASI bus) have to be supported. Technical parameters: a) Memory: 4GB Ms. HDI Piyumini Frame rate: 40 CAMERA CMOS Communication mode: RS232 / Ethernet / parallel / Io UI operation: mouse Number of cores: 4 cores Shutter function: within 100ms Effective pixels: 720 * 540 Setting method: create the process Closed Loop Conveyor to mount the stop stations and carry the pallets. 10 working temperature: 0-40 °C

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Machine

General requirements of visual inspection unit:

12. Size(L×W×H): Ø30×75mm

Vision System

The visual inspection unit receives the signal from the upper computer, takes pictures, processes the

results, and returns them to the upper computer to judge whether the workpiece is qualified.

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Lecturer (Probationary)

The conveyor has to stop alongside each CIM workstation. Include magnetic sensors for pallet detection and pneumatic pistons for halting and releasing the pallets.

and operations CIM software should provide a comprehensive solution for the study and practice of CIM/FMS methods

subsystems through a LAN, a lab network, or the Internet real-time information with the system's PC-based database, and maintain online communication with all CIM software should implement manufacturing execution system (MES) technology. It should integrate

live production cycles in and view details of current CIM/FMS cell status. locations., users should be able to view real-time reports generated by the CIM manager, remotely track The CIM software should allow users to monitor CIM/FMS cell operations in real-time from remote

components, making it easy to expand and customize the CIM/FMS system. The CIM software open architecture should enable the integration of various hardware and software

control of intelligent manufacturing unit; the touch screen is responsible for human-machine interface is mainly responsible for peripheral equipment and robot control to realize the process and logic general and setting operation data The Management Station should include PLC electrical control and I / O communication system, which

Technical Parameter

- a) Communication port: Ethernet
- b) 2.I/O:>=32
- c) Input Type: NPN/PNP

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	General Terms	Gener
r) Compatible with other items in the trainer and furniture.	1	
q) PLC approvals: CE mark, UL, cULus FM, RCM (formerly C-TICK), KC, Marine	•	
instruction		
operations, typ. 1.6-1.7 μs; / instruction o for floating point arithmetic, typ. 2.2-2.3 μs; /		
p) Preferred CPU processing times o for bit operations, typ. 0.07 -0.09 μs; / instruction o for word		
o) The units are supplied fully assembled		

- Manufacturer authorization letter
- Warranty 1-year
- 3. Country of Origin UK, EU, Japan, USA,
- Only reputed brands are accepted
- Product support 10 years
- 6. Annual maintenance arrangement to be signed by successful bidder
- Comprehensive training for 5 personal
- All manuals should be in English (workshop manual, spare part catalogue, operations manual)
- 9. Standard set of operation tools, cutting tools and coolants

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Proposed practical for sorting Metal and Non-Metal items:

- Objects are placed on a conveyor belt
- 2. A sensor identifies the object
- 3. When the object is present (identified) the conveyor starts to run.
- 4. There will be a light indicating that the conveyor is running.
- 5. The object is passing an inductive sensor.
- If Inductive sensor detects the object (metals), a pneumatic actuator pushes the object into a basket in front of sensor (side of conveyor).
- 8. After the operation is over, the conveyor will stop. (timed)

If not, the object will fall into the basket at the end of the conveyor.

). Light will also turn off.

Proposed practical for Sorting objects based on color:

- Objects are placed on a conveyor belt
- . A sensor identifies the object
- When the object is present (identified) the conveyor starts to run.
- 1. There will be a light indicating that the conveyor is running.
- The object is passing through red detecting and blue detecting sensors respectively.
- If either one of the sensors detects the object (metals), a pneumatic actuator corresponding to that particular sensor pushes the objects into a basket in front.
- If not (any other color) the object will fall into the basket at the end of the conveyor.
- After the operation is over, the conveyor will stop. (timed)
- . Light will also turn off.

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Annexure I

Expected functions for the standalone operation

enables the robot to differentiate workpieces by colour (black/non-black). The sensor in the assembly retainer monitors the orientation of the the springs out of a slim magazine. The assembled workpiece is placed on a slide. workpiece. From the assembly retainer the robot sorts the workpieces into various magazines or passes them on to the downstream station. A double-acting cylinder pushes the cylinder caps out of the stacking magazine. The pistons are stored on a pallet. A double-acting cylinder pushes Workpieces can be assembled in combination with the process module robot assembly. It supplies cylinder components for the assembly process. The robot assembly station can transport workpieces that are fed via a slide and place them in an assembly retainer. The sensor in the gripper

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SPECIMEN FORM OF BID SECURITY										
By this Bond we	held and sum of									
bind themselves their successors and assigns jointly and severally by those presents.										
Whereas the authority has invited the Tender and other persons to compete tenders in similar terms for the	supply									
of	a area ftor									
called "the Bid") in accordance with such invitation, the Bond shall provide security to the Authority that the Bid honour certain obligations to be undertaken by him in the Tender in accordance with the following conditions. Now the Conditions of this Bond are:										
(a) That it shall remain in full force and effect until the earliest of										
(u) That it shall remain in full lorde and effect until the carriest of										
(i) (Date), being () days from (submission date), the date stipulated by the Authority submission of tenders, or any prolongation of such date above notified to the Authority by the Bi the Surety in writing.										
(ii) In the event of acceptance of the Tender by the Authority, the date upon which the provides a performance security to the Authority in accordance with the terms of the contract made between them, or	Bidder thereby									
(b) Subject to this Bond being in full force and effect, the Surety shall pay the full amount specified	l in thic									
Bond upon receipt of first written demand form the Authority stating that.	i ili ulis									
(i) The Bidder has withdrawn his Tender during the validity of this Bond, or										
(ii) The Bidder has failed to provide a performance security to the Authority in accordance with terms of the tender within 14 days from receipt of intimation of award of the Tender.										
No alteration in the terms of the Tender, nor any forbearance of forgiveness in or in respect of neither an or thing concerning the Tender on the part of the Authority, nor any objection from the bidder shall in any way resurety from any liability under this Bond.	y matter ease the									
The benefit of this Dand shall not be assignable by the Authority and year its assign to be in full forms	1 - 604									
The benefit of this Bond shall not be assignable by the Authority and upon its ceasing to be in full force at the Authority shall return the same to the Bidder. This Bond shall be governed by the laws of Sri Lanka	d effect									
I executed as a deed on this () day of () 20 ()										
For and on behalf of the Bidder For and on behalf of the Surety										
Signed by Signed by										
In the capacity of In the capacity of										
and by and by										
In the capacity of In the capacity of										

Seal (where applicable)

Seal (where applicable)

DELIVERY SCHEDULE

QTY :		•••••	
DURATION		QTY	
EX STOCK QTY (WITHIN	01 WEEK)		
01MONTH			
02 MONTHS			
03 MONTHS			
04 MONTHS			
TOTAL			
	larger bander (gr		
AME OF THE BIDDER	:		 ••••••
IGNATURE OF BIDDER	· · · · · · · · · · · · · · · · · · ·		
ATE	:		